

Compositi Expo-congress
Modena ,14 Ottobre 2009

Topological optimization of the stiffener and layup of a rear wing sport car

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Agenda

- Exemplar srl
 - composite design know-how
- Problem introduction
 - layup definition
 - spars introduction
- iDA optimization tool
 - Features description
 - Why iDA
 - Graphical interface
 - iDA method
- Wing box Results
- Questions & Answer



Exemplar and the composite design

- 12 years of experience in composite simulation
 - Aerospace, Automotive and Ship building
 - Aeroelasticity analysis
 - Static, Buckling and Dynamic analysis
 - Composite certification/verification for aeronautical industries
- R&D and founded project with innovative composite material
 - Green composite research with ALENIA
 - Nanotube application on composite on "TOP" project with ALENIA-THALES Space
- Training and technological update
 - Know-how transfer
 - Training on the job
- Software development for composite optimization
 - Dedicated interface for CAE solver

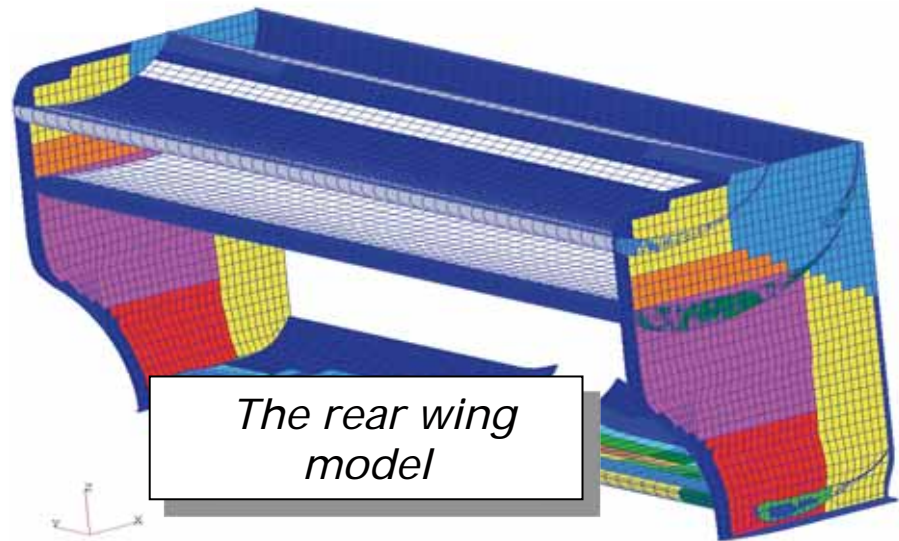


Problem introduction

- Problem description
- The iDA [*i*ntelligent *D*ecision *A*dvisor] software was been used to design a new layup for the full rear wing sport car and to investigate about the best position for the internal spar:
 - assure adequate static capability and buckling performance
 - assure the required stiffness for the auditor certification
 - assure high flexional frequency vibration
 - reduce the weight respect to the actual design
 - define the best spar number and position

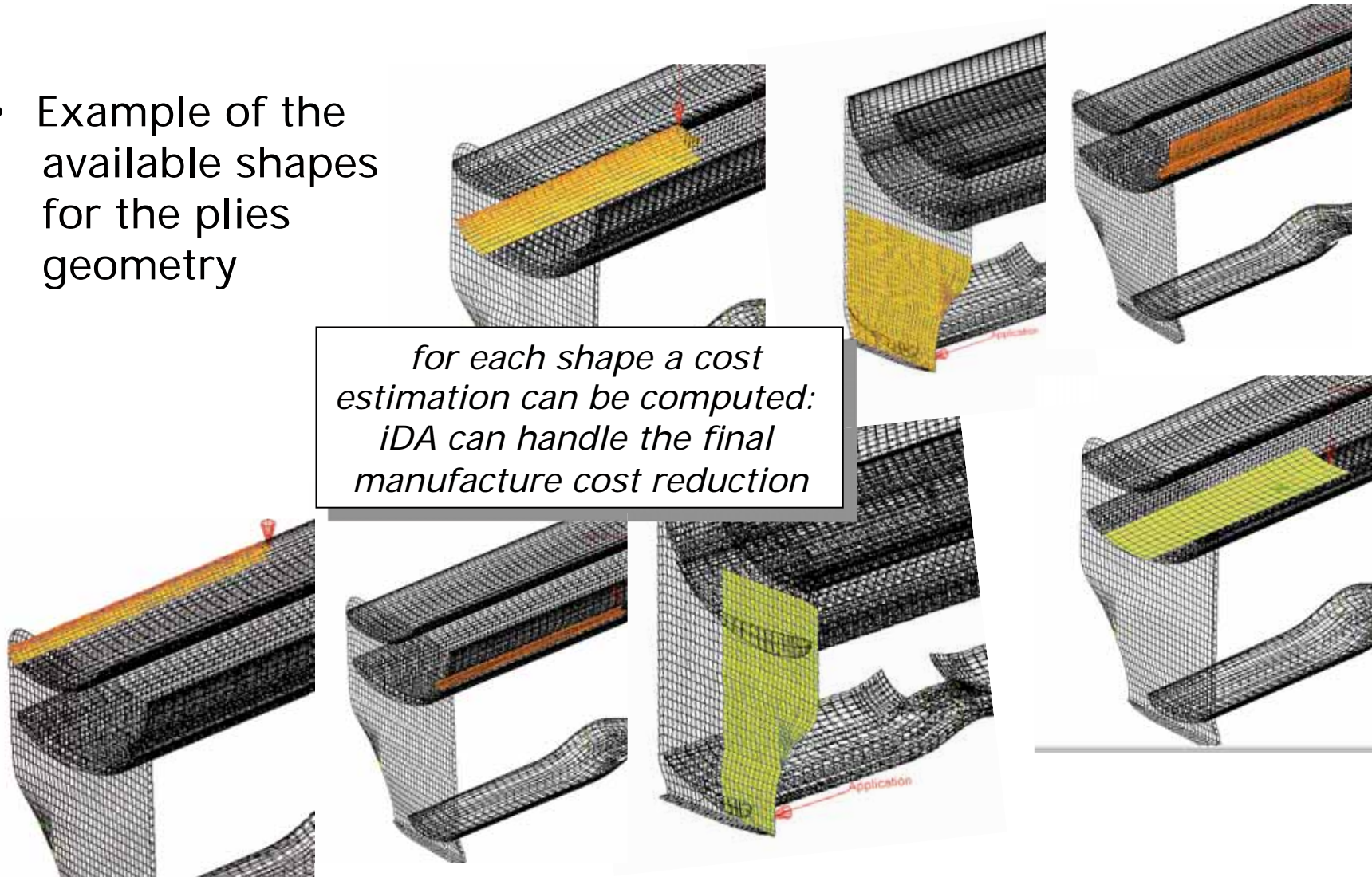
Problem introduction

- The external shape cannot be modify
- 250 ply shapes are available
- angle ply step by 5°
- each ply can be chosen from a material list
- The problem has about 800 indipendent parameters

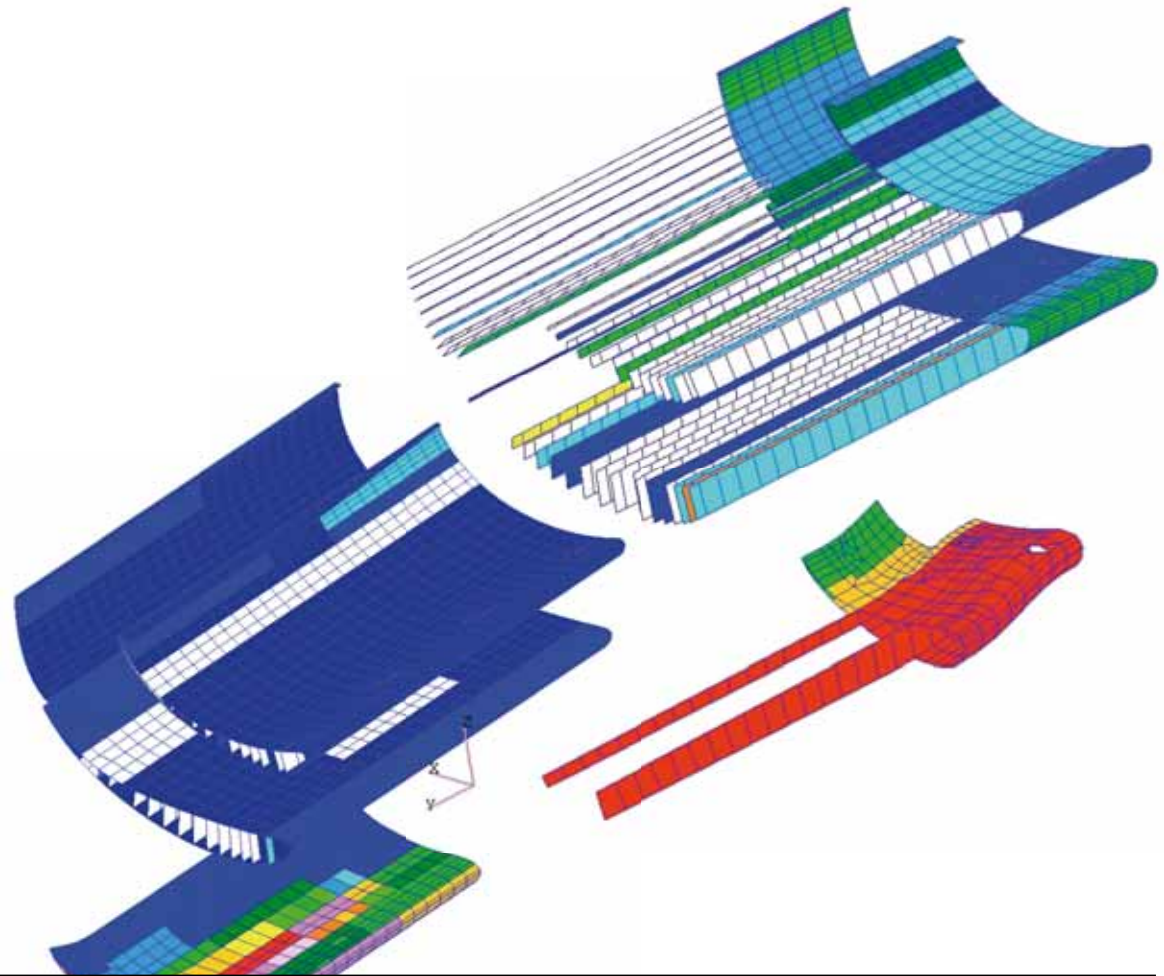


- Example of the available shapes for the plies geometry

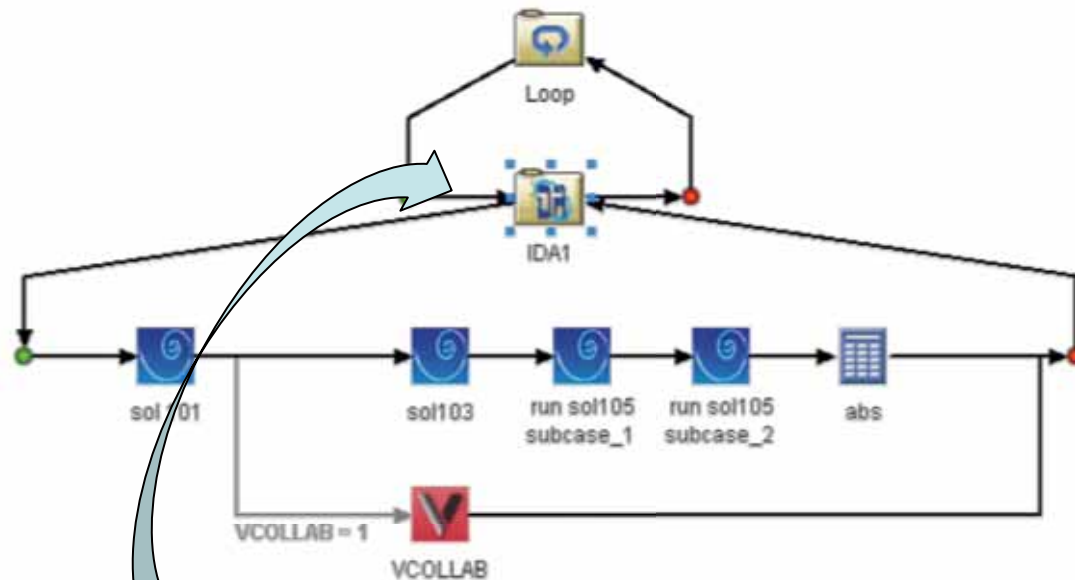
*for each shape a cost estimation can be computed:
iDA can handle the final
manufacture cost reduction*



- The internal wings have been filled with spars (50 spars)



The internal spar distribution in the wings



The iSight-FD workflow with iDA used to solve HT structural problem

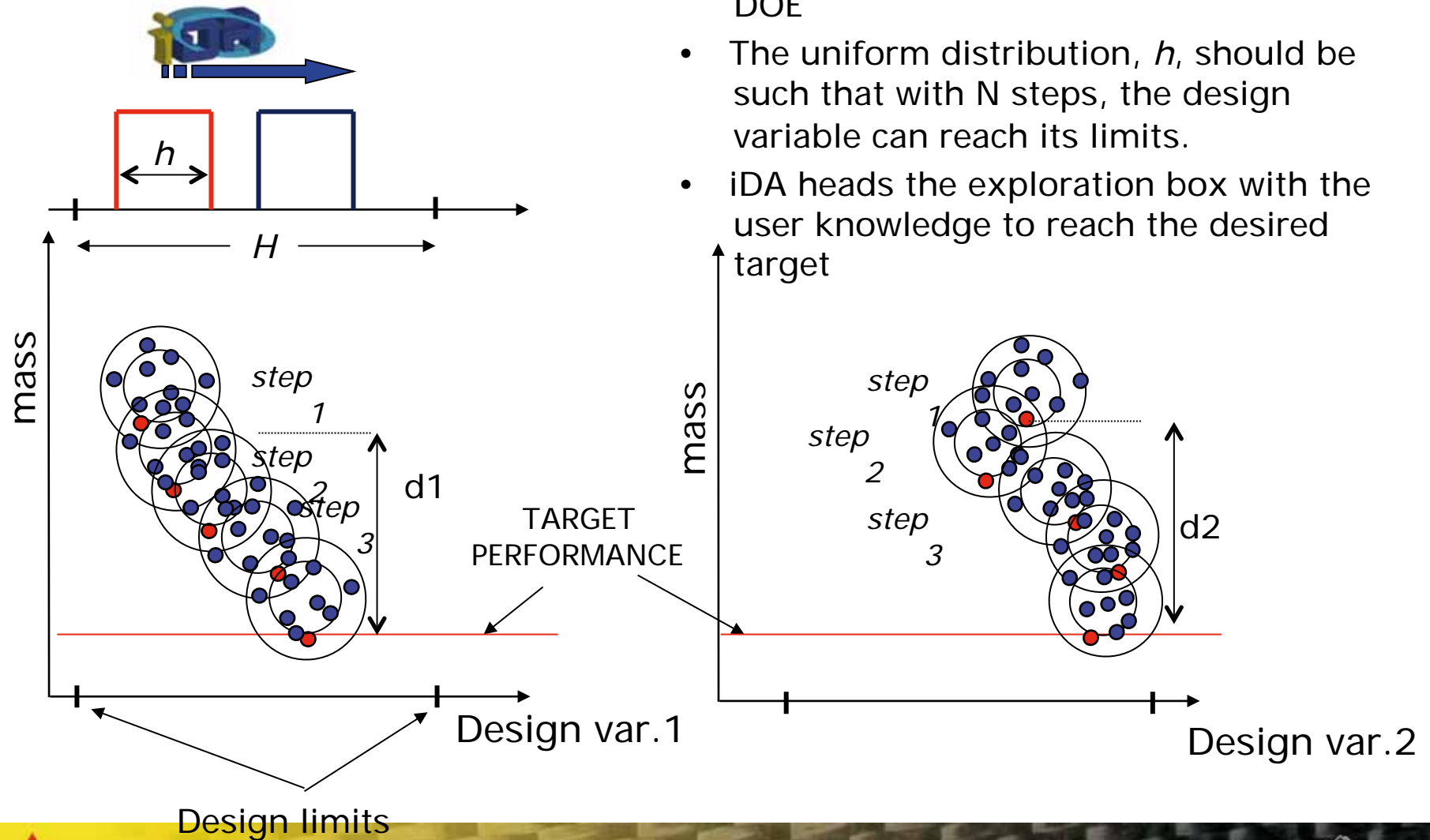
- iDA is a algorithm able to improve the design in the real world environment (limited time, limited resources, complex problem)
- iDA has been developed by EXEMPLAR team. It collects 10 years of experience on optimization problem for the industry.
- iDA is also available as a plug-in on iSight process integration software.



Why ?

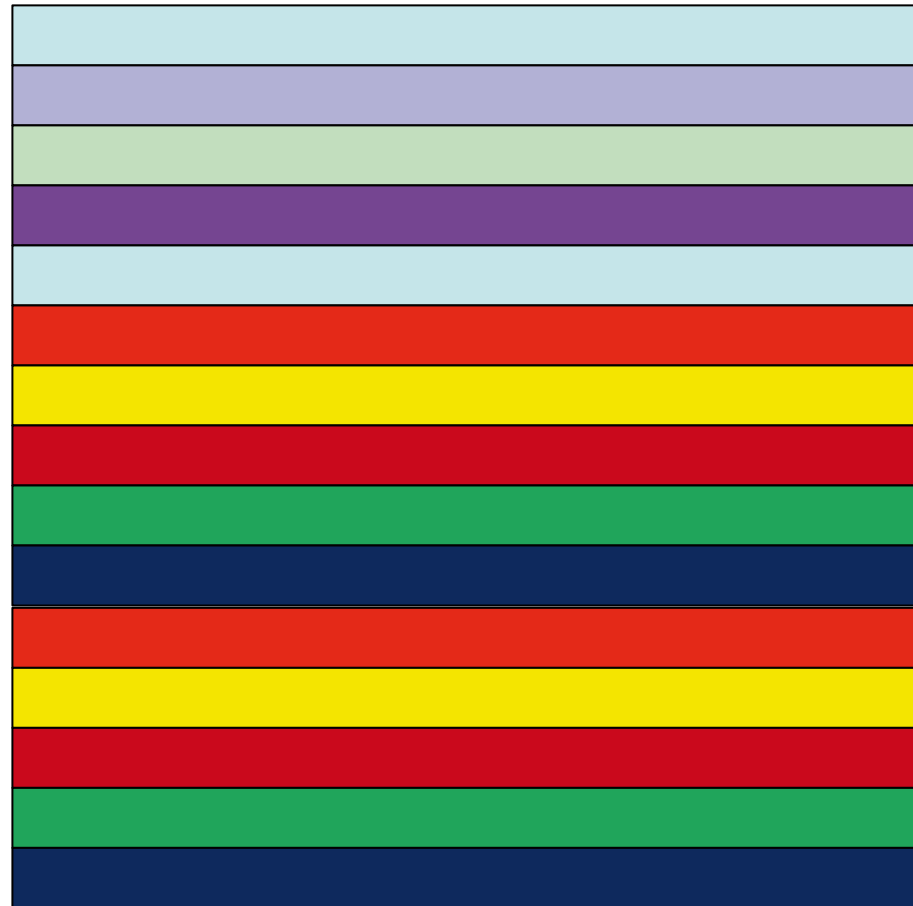
- The multi-disciplinary optimization problem dramatically increase the design parameter: in the real world, the number of design parameter is huge, and only an efficient exploration of their interaction can achieve a innovation design.
- For engineering problems many optimization method are available. EXEMPLAR experienced that all of them have a maximum number of design parameter limit, because they are “generic” method.
- In the classical optimization methods, the user cannot supply his knowledge about the studied system.
- The aim of iDA method is allow the expert to supply all available useful information which can help the exploration method to reach its goals.

The iDA method

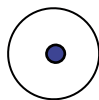


- iDA can be "briefly" defined as a drove DOE
- The uniform distribution, h , should be such that with N steps, the design variable can reach its limits.
- iDA heads the exploration box with the user knowledge to reach the desired target

GLOBAL LAYUP SEQUENCE: the independent plies



PLY NAME	ANGLE	MATERIAL
Ply_shape_#1000	angle=0°	Mat=A
Ply_shape_#1010	angle=0°	Mat=A
Ply_shape_#1012	angle=0°	Mat=A
Ply_shape_#1020	angle=0°	Mat=A
Ply_shape_#1000	angle=0°	Mat=A
Ply_shape_#2040	angle=0°	Mat=A
Ply_shape_#2045	angle=0°	Mat=A
Ply_shape_#2044	angle=0°	Mat=A
Ply_shape_#1072	angle=0°	Mat=A
Ply_shape_#1045	angle=0°	Mat=A
Ply_shape_#2040	angle=0°	Mat=A
Ply_shape_#2045	angle=0°	Mat=A
Ply_shape_#2044	angle=0°	Mat=A
Ply_shape_#1072	angle=0°	Mat=A
Ply_shape_#1045	angle=0°	Mat=A



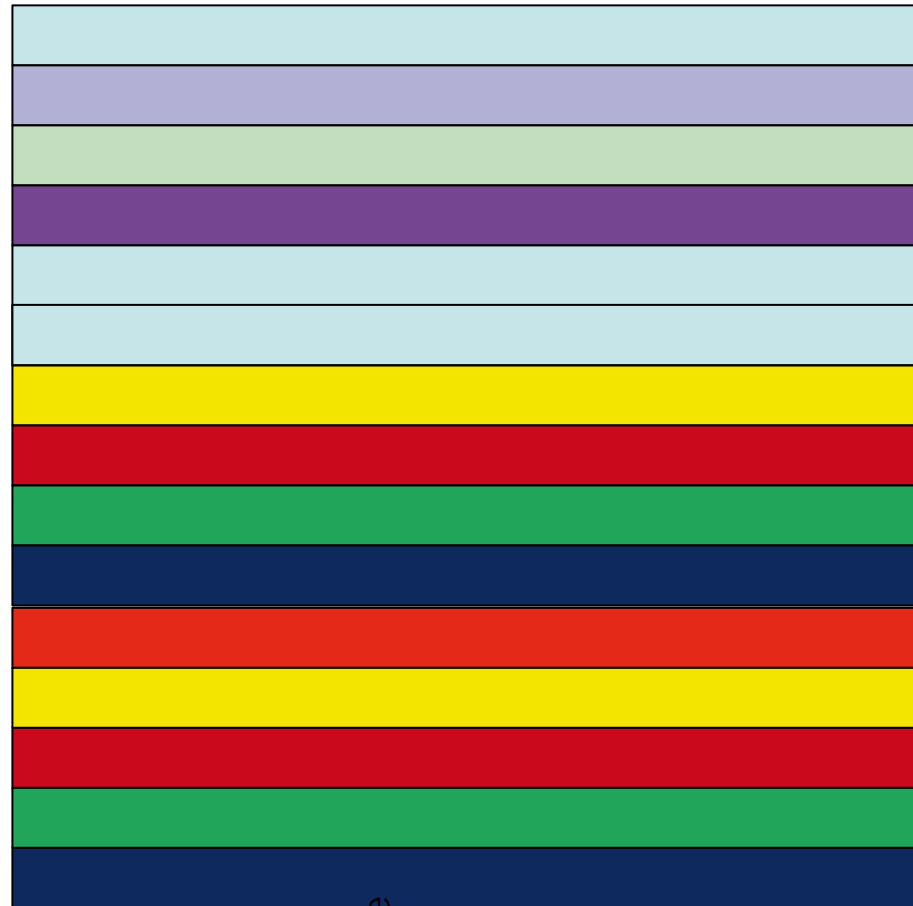
STEP -0- : initial configuration

- In the composite design, iDA doesn't consider the parameter like thickness, angles or materials as cardinal numbers, but it manages them as "configuration state"
- A stochastic distance is defined for each design parameter: the ply shape, the angle and the ply material;
the list table of all these parameters is a "configuration state"
- The Euclid distance between the configuration state and the user desired performance is automatically computed based on the user physics consideration.
- At the step -0-, each parameter has the maximum distance to the desired target performance

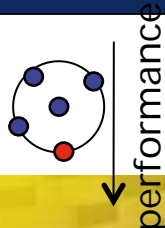
GLOBAL LAYUP SEQUENCE: the independent plies

	PLY NAME	ANGLE	MATERIAL
	Ply_shape_#1000	angle=45°	Mat=A
	Ply_shape_#1010	angle=0°	Mat=B
	Ply_shape_#1012	angle=90°	Mat=A
	Ply_shape_#1020	angle=0°	Mat=C
	Ply_shape_#1000	angle=45°	Mat=C
	Ply_shape_#2040	angle=45°	Mat=A
	Ply_shape_#2045	angle=0°	Mat=B
	Ply_shape_#2044	angle=0°	Mat=A
	Ply_shape_#1072	angle=90°	Mat=B
	Ply_shape_#1045	angle=45°	Mat=A
	Ply_shape_#2040	angle=90°	Mat=A
	Ply_shape_#2045	angle=45°	Mat=B
	Ply_shape_#2044	angle=0°	Mat=C
	Ply_shape_#1072	angle=0°	Mat=B
	Ply_shape_#1045	angle=45°	Mat=A

GLOBAL LAYUP SEQUENCE: the independent plies




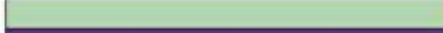










PLY NAME	ANGLE	MATERIAL
Ply_shape_#1000	angle=0°	Mat=A
Ply_shape_#1010	angle=0°	Mat=A
Ply_shape_#1012	angle=0°	Mat=A
Ply_shape_#1020	angle=0°	Mat=A
Ply_shape_#1000	angle=0°	Mat=A
Ply_shape_#1000	angle=0°	Mat=A
Ply_shape_#2045	angle=0°	Mat=A
Ply_shape_#2044	angle=0°	Mat=A
Ply_shape_#1072	angle=0°	Mat=A
Ply_shape_#1045	angle=0°	Mat=A
Ply_shape_#2040	angle=0°	Mat=A
Ply_shape_#2045	angle=0°	Mat=A
Ply_shape_#2044	angle=0°	Mat=A
Ply_shape_#1072	angle=0°	Mat=A
Ply_shape_#1045	angle=0°	Mat=A



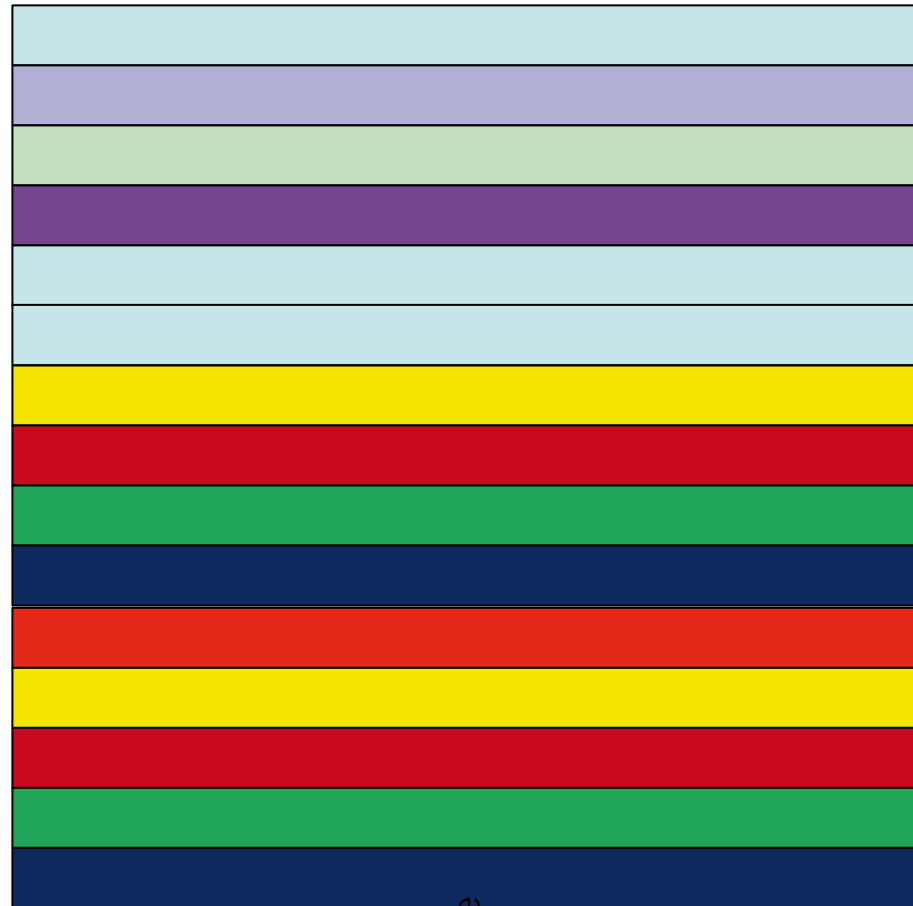
STEP -1- : first design exploration

- The history of the evolution of each design parameters (shape, thick, mat, etc..) and the history of the evolution of the performance's "configuration state" are related such as a cardinal ordering in the stochastic metric is created
- The stochastic distance of the parameters is used to chose which parameter will be in the next iDA step perturbed

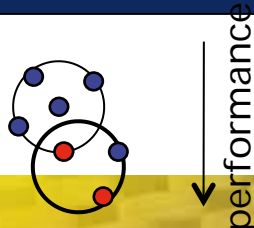
GLOBAL LAYUP SEQUENCE: the independent plies

	PLY NAME	ANGLE	MATERIAL
	Ply_shape_#1000	angle=45°	Mat=A
	Ply_shape_#1010	angle=0°	Mat=B
	Ply_shape_#1012	angle=90°	Mat=A
	Ply_shape_#1020	angle=0°	Mat=C
	Ply_shape_#1000	angle=45°	Mat=C
	Ply_shape_#2040	angle=45°	Mat=A
	Ply_shape_#2045	angle=0°	Mat=B
	Ply_shape_#2044	angle=0°	Mat=A
	Ply_shape_#1072	angle=90°	Mat=B
	Ply_shape_#1045	angle=45°	Mat=A
	Ply_shape_#2040	angle=90°	Mat=A
	Ply_shape_#2045	angle=45°	Mat=B
	Ply_shape_#2044	angle=0°	Mat=C
	Ply_shape_#1072	angle=0°	Mat=B
	Ply_shape_#1045	angle=45°	Mat=A

GLOBAL LAYUP SEQUENCE: the independent plies



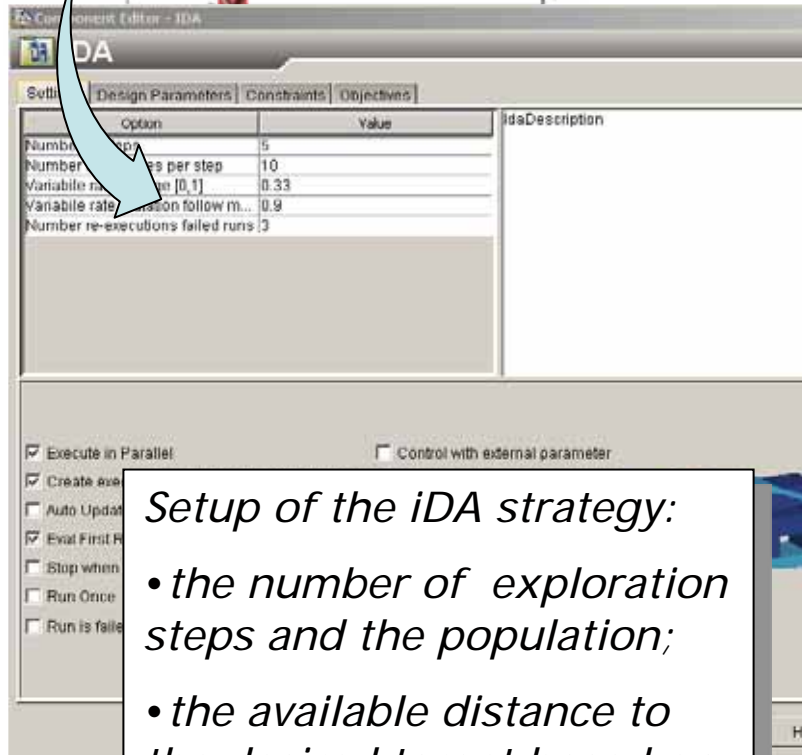
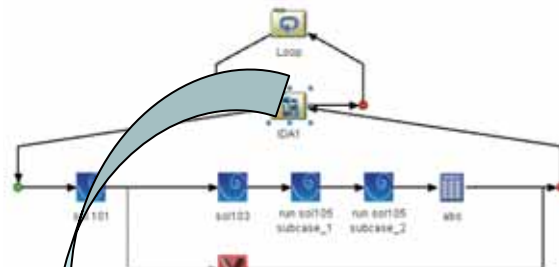
PLY NAME	ANGLE	MATERIAL
Ply_shape_#1000	angle=0°	Mat=A
Ply_shape_#1010	angle=0°	Mat=A
Ply_shape_#1012	angle=0°	Mat=A
Ply_shape_#1020	angle=0°	Mat=A
Ply_shape_#1000	angle=0°	Mat=A
Ply_shape_#1000	angle=0°	Mat=A
Ply_shape_#2045	angle=0°	Mat=A
Ply_shape_#2044	angle=45°	Mat=A
Ply_shape_#1072	angle=0°	Mat=A
Ply_shape_#1045	angle=90°	Mat=A
Ply_shape_#2040	angle=0°	Mat=A
Ply_shape_#2045	angle=0°	Mat=C
Ply_shape_#2044	angle=0°	Mat=A
Ply_shape_#1072	angle=0°	Mat=A
Ply_shape_#1045	angle=0°	Mat=A



STEP -2- : next step design exploration

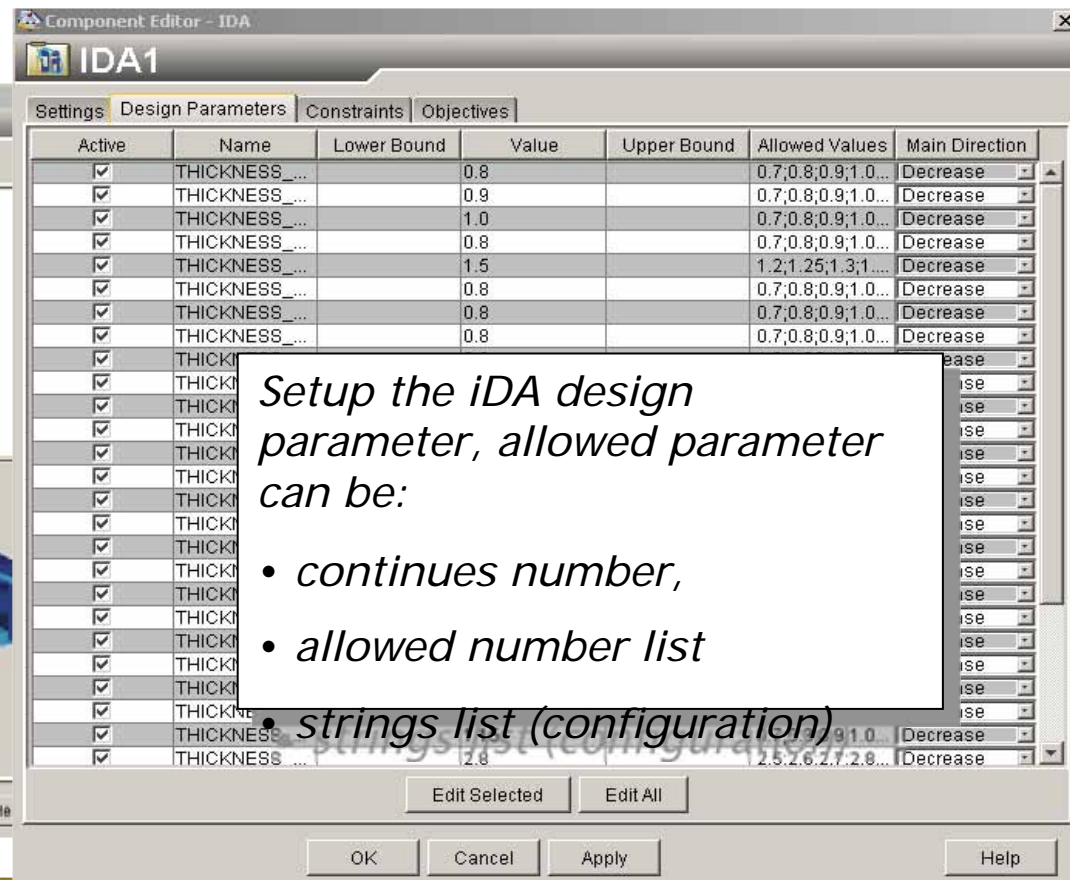
The iDA graphical interface

- iDA has a GUI to quickly setup the engineering problem.



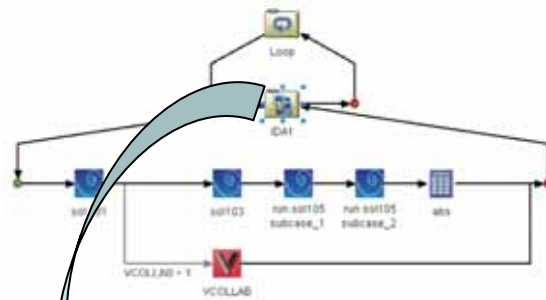
Setup of the iDA strategy:

- the number of exploration steps and the population;
- the available distance to the desired target based on physic consideration



Setup the iDA design parameter, allowed parameter can be:

- continues number,
- allowed number list
- strings list (configuration)



- Constrains and target can be defined using engineering sense.

Component Editor - IDA

IDA1

Settings | Design Parameters | Constraints | Objectives

Active	Name	Lower Bound	Upper Bound	Weight	Soft
<input checked="" type="checkbox"/>	Cycle_1_sub120	17.3		1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	Cycle_2_sub120	36.2		1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	Eigenvalue_1_su...	0.8		1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	Eigenvalue_1_su...	0.8		1	<input type="checkbox"/>
<input type="checkbox"/>	MASS			1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	NumEle_Vonmis...		2	1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	NumEle_Vonmis...		2	1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	NumEle_Vonmis...		2	1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	NumEle_Vonmis...		2	1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	NumEle_Vonmis...		2	1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	NumEle_Vonmis...		2	1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	NumEle_Vonmis...		2	1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	NumEle_Vonmis...		2	1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	NumEle_Vonmis...		2	1	<input type="checkbox"/>
<input checked="" type="checkbox"/>	NumEle_Vonmis...		2	1	<input type="checkbox"/>

Setup of the problem constrain:

- "engineering soft" constrains can be used: design sense

Edit Selected Edit All

OK Cancel Apply Help

Component Editor - IDA

IDA1

Settings | Design Parameters | Constraints | Objectives

Active	Name	Direction	Value	Weight
<input type="checkbox"/>	THICKNESS_PSHEL...			1
<input type="checkbox"/>	Eigenvalue_1_sub122			1
<input type="checkbox"/>				1
<input type="checkbox"/>				1
<input type="checkbox"/>				1
<input type="checkbox"/>				1
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<input type="checkbox"/>				1
<input type="checkbox"/>				1
<input type="checkbox"/>				1
<input type="checkbox"/>				1
<input type="checkbox"/>				1
<input checked="" type="checkbox"/>	MASS	Less than...	1500	1
<input type="checkbox"/>	THICKNESS_PSHEL...			1
<input type="checkbox"/>	THICKNESS_PSHEL...			1
<input type="checkbox"/>	THICKNESS_PSHEL...			1
<input type="checkbox"/>	THICKNESS_PSHEL...			1
<input type="checkbox"/>	THICKNESS_PSHEL...			1
<input type="checkbox"/>	VCOLLAB			1

Setup the desired system target: do not use the minimize or maximize concept, but define the engineer desired system performance

Edit Selected Edit All

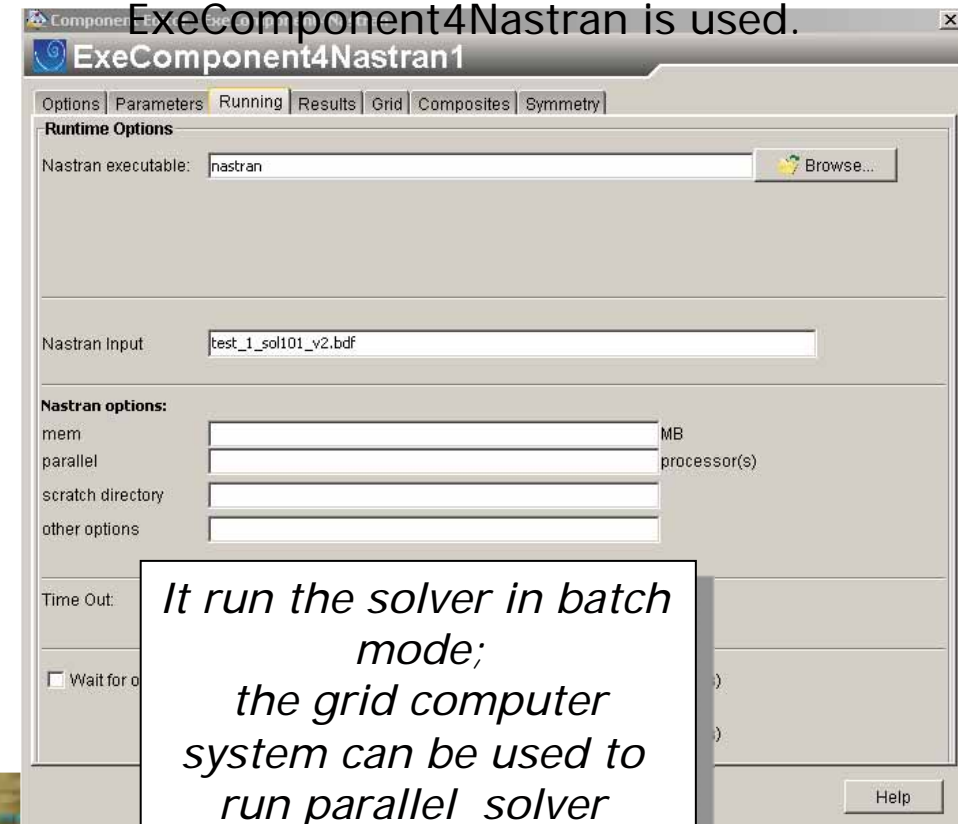
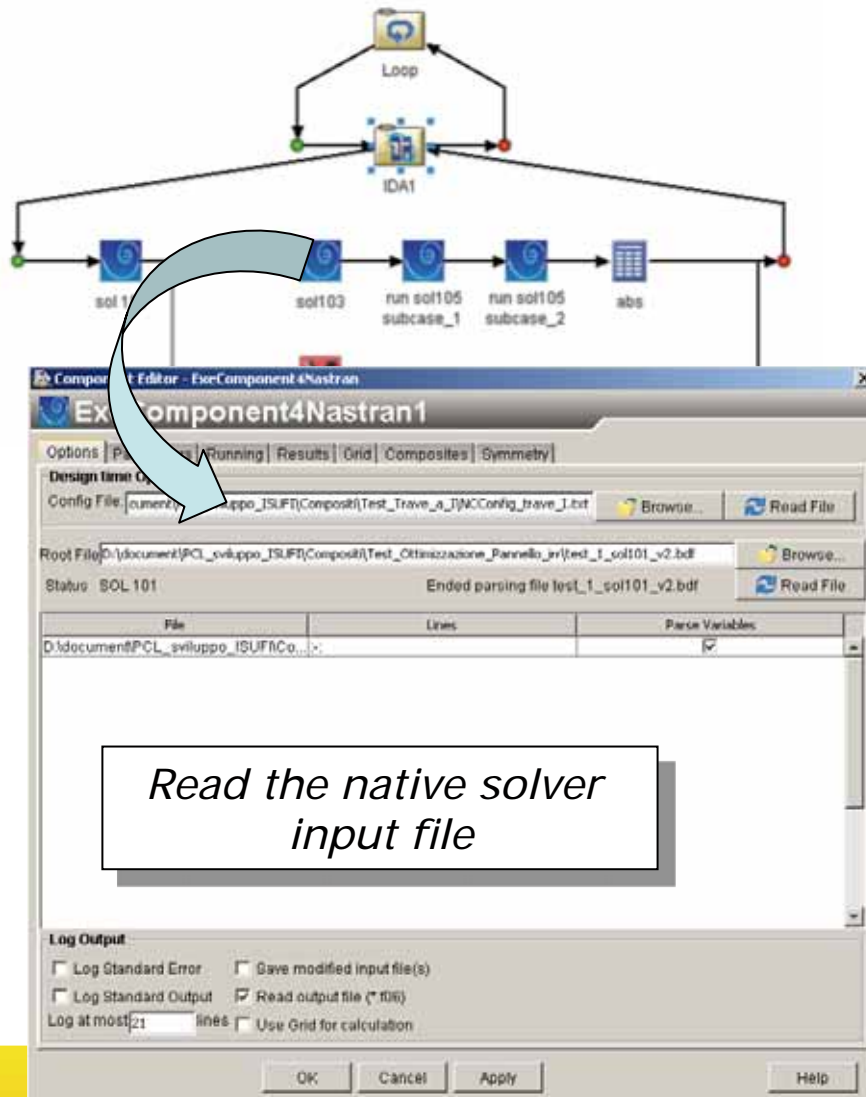
OK Cancel Apply Help

The final recipe:



- The iDA generic interface can handle all kind of optimization problem
- But a dedicated interface has been developed for a quick composite complex problem setup, based on rules design.
- In the current example the

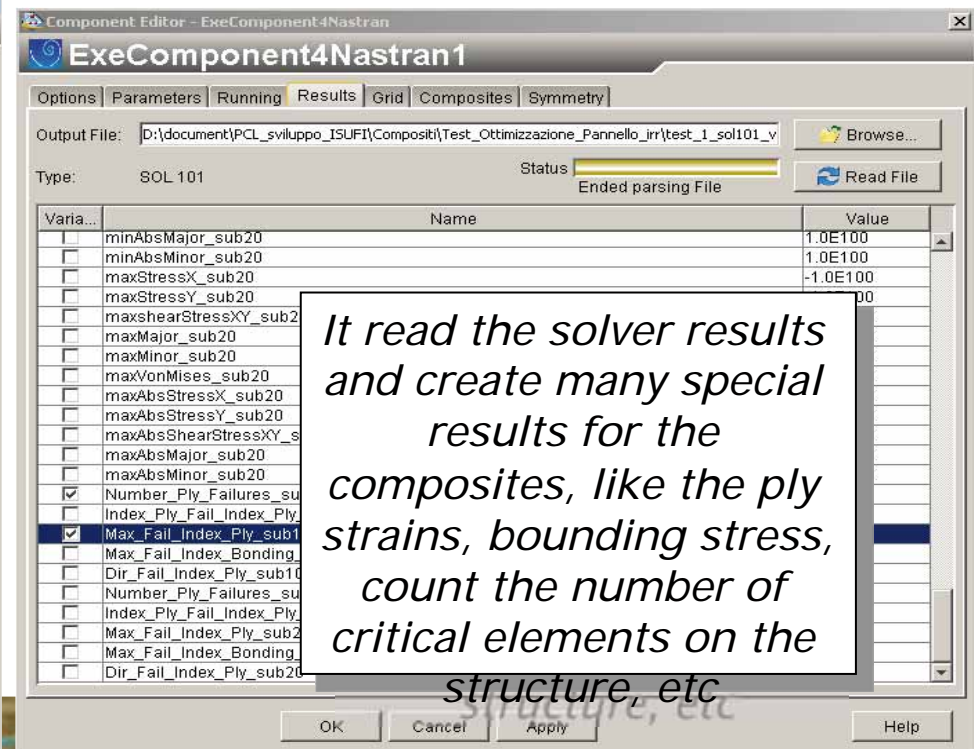
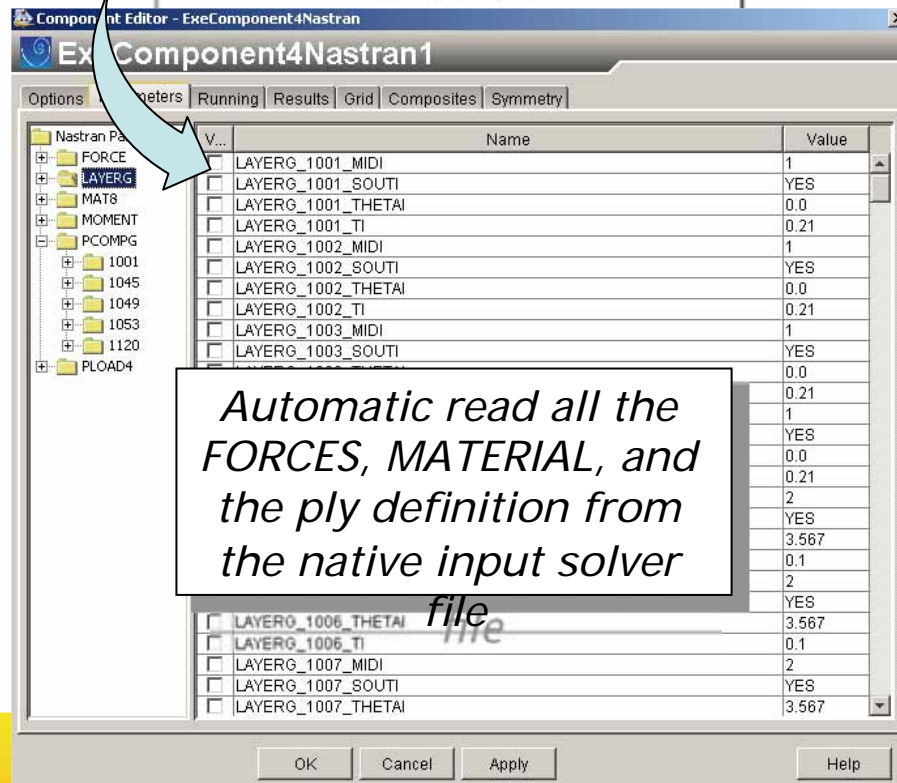
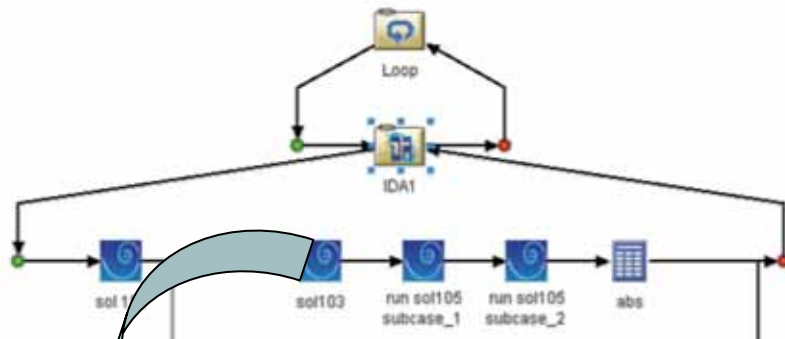
ExeComponent4Nastran is used.



The final recipe:



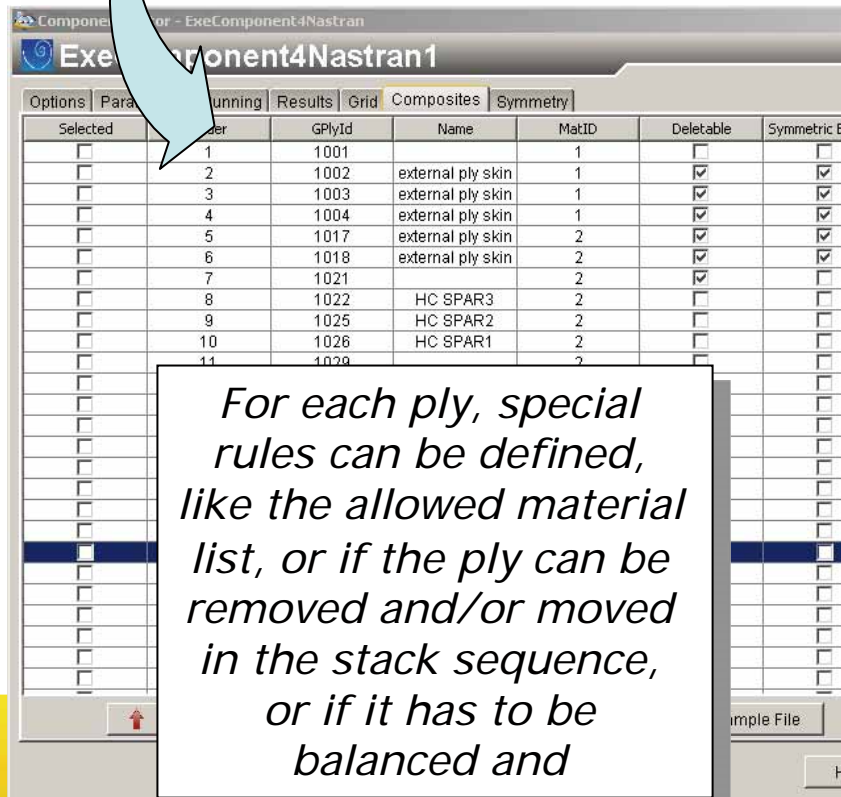
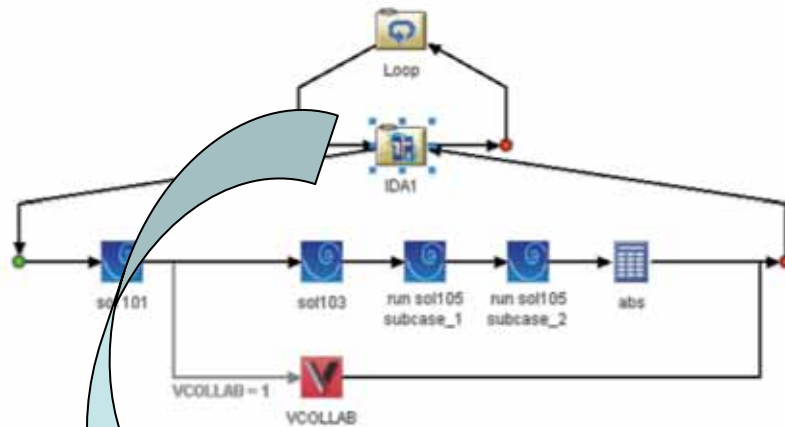
- ExeComponent4Abaqus and ExeComponent4Ansys are also available.



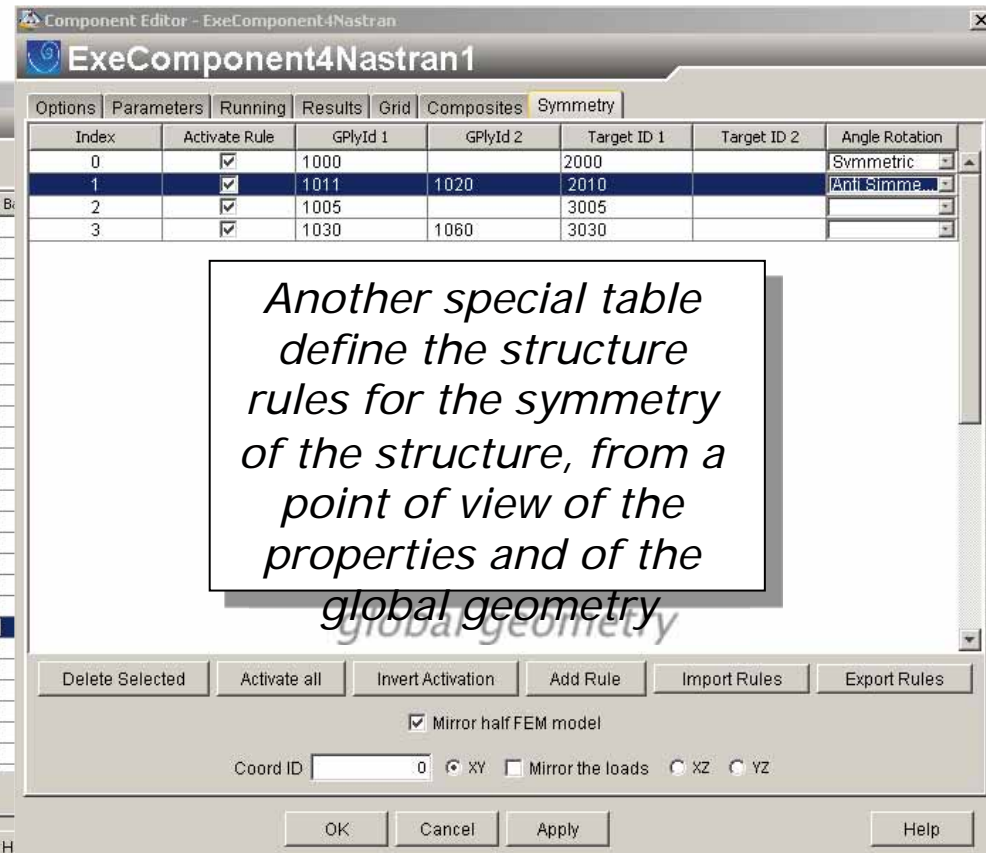
The final recipe:



- Local layup rules
 - \$ symmetric and balanced
 - \$ external wrapper
 - \$ sandwich behaviour, etc
- Global layup rules
 - \$ Defined by the shape of the manufacture



For each ply, special rules can be defined, like the allowed material list, or if the ply can be removed and/or moved in the stack sequence, or if it has to be balanced and symmetrical defined

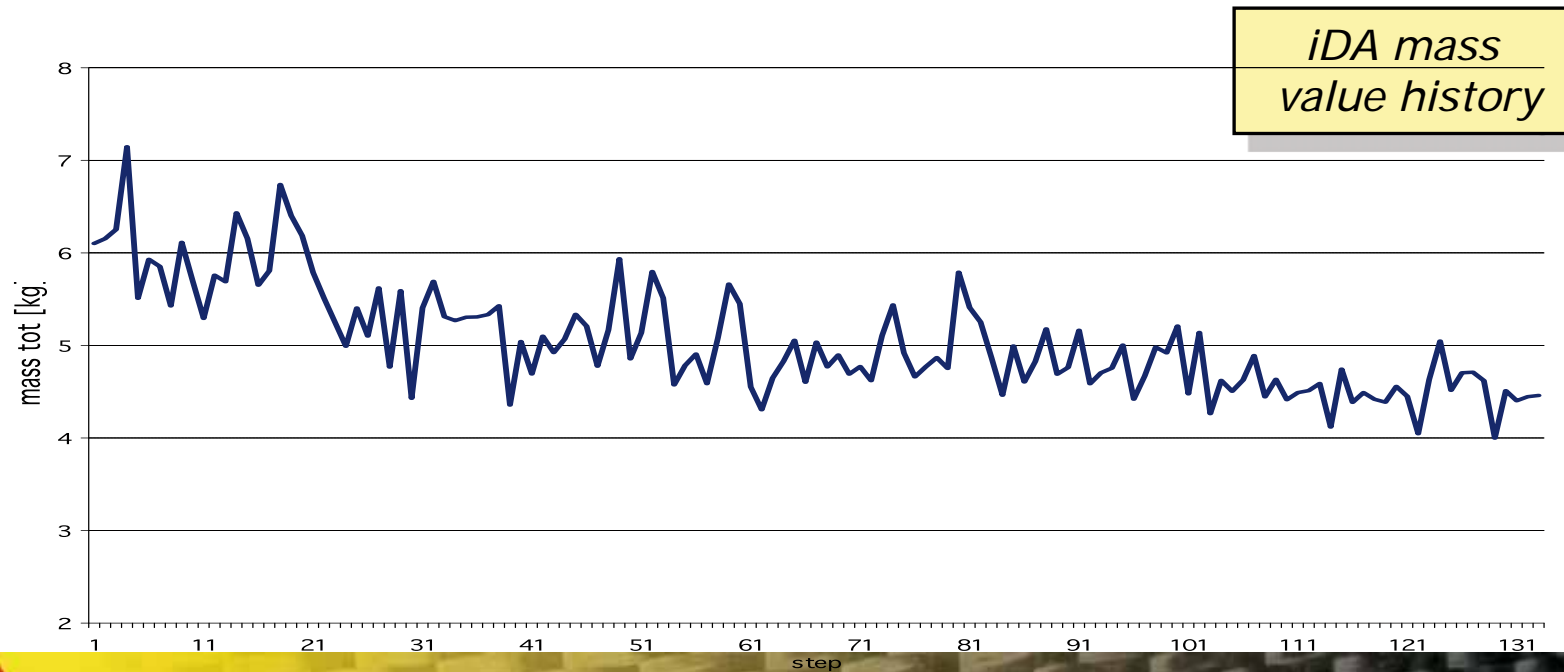


Another special table define the structure rules for the symmetry of the structure, from a point of view of the properties and of the global geometry

Results

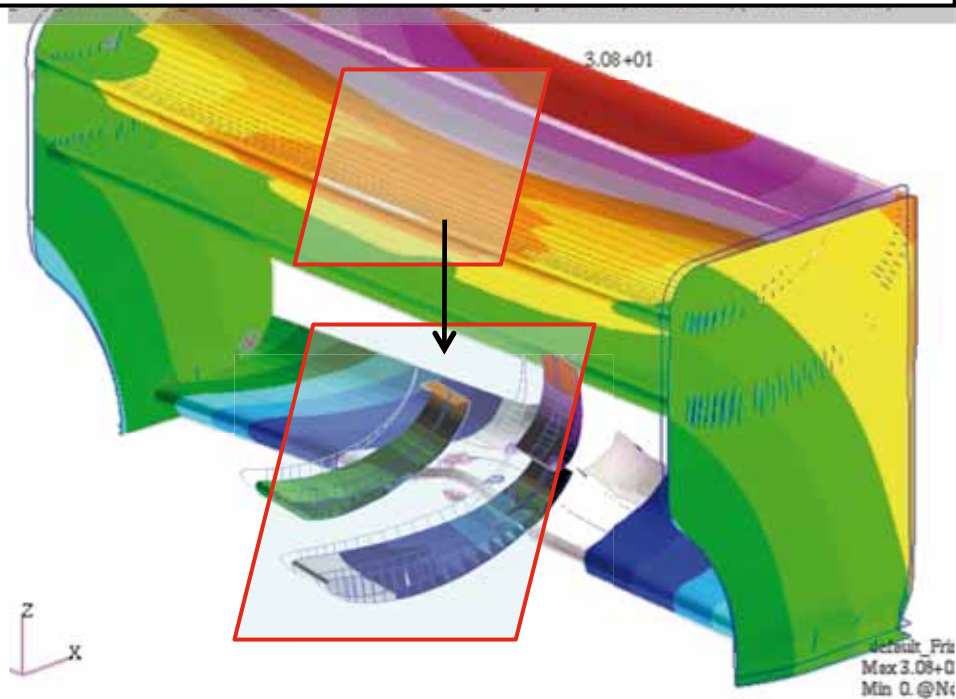
- 131 function evaluations have been used to reduce weight and achieve the desired performance
- 15.0% weight reduction on the initial design

	Initial Design	iDA Result	Variation
Mass of the component	1	0,847	-15.3%
Requirement stiffness	0,893	0,952	+6%
Flexional freq.	21,17	24,5	+14%

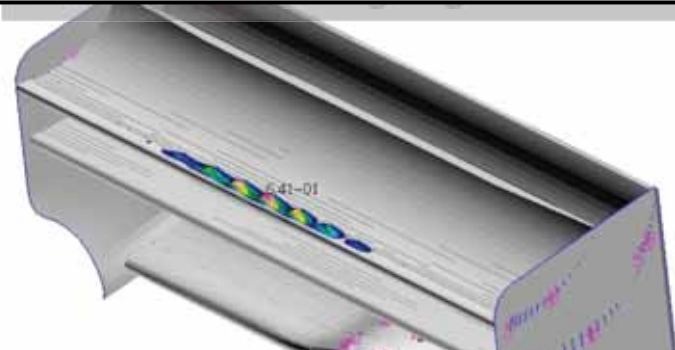


Results

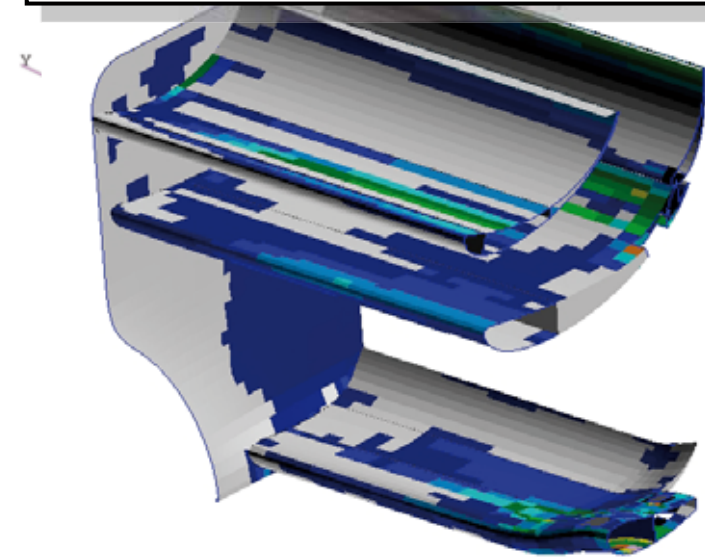
Static deformation under pressure load

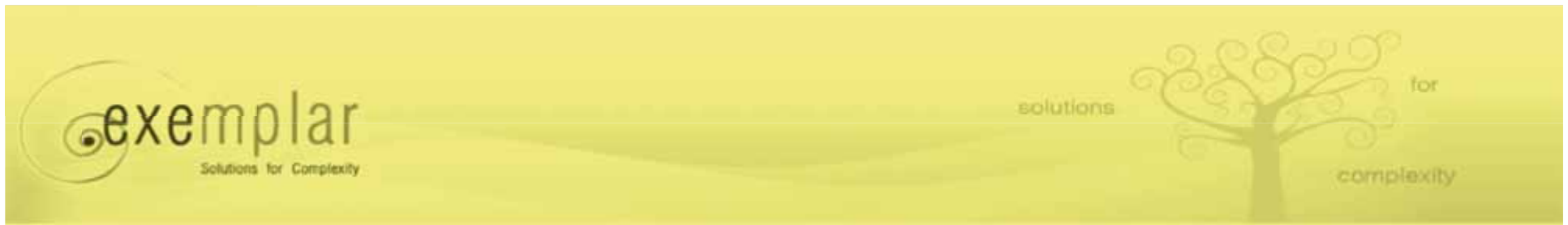


First buckling eigenvector



Margin of Safety plot





- Questions?

